

Lecture 1

Discrete-Time Signals and Systems

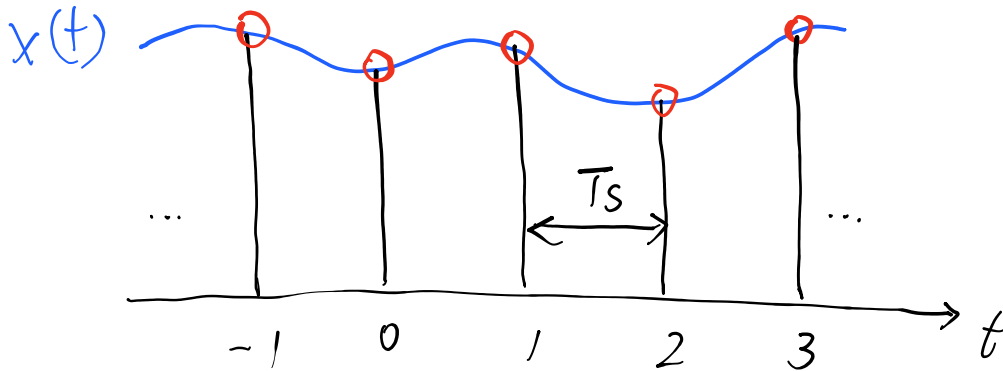
Signals: Functions of variables (Time, Time Index)

$x(t)$
 \downarrow
 Continuous - time

$x[n]$
 \downarrow
 discrete - time , where n is an integer

Digital Signals: discrete both in time and amplitude

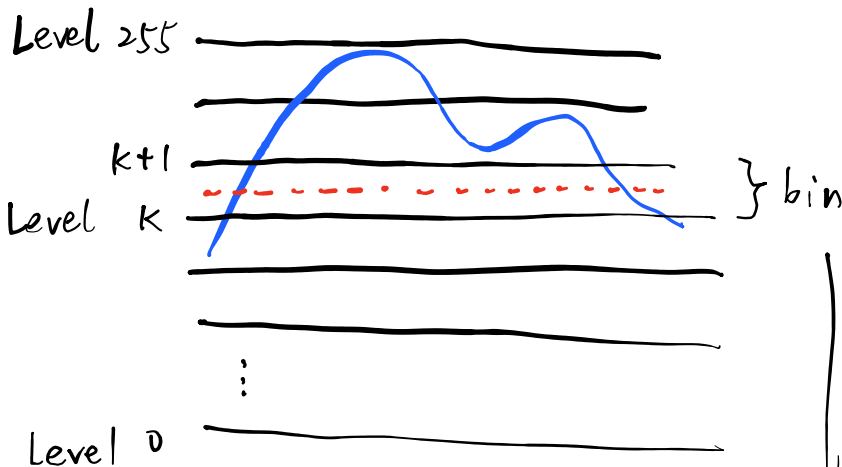
Digitization : $\left\{ \begin{array}{l} \text{Sampling : } x(t) \rightarrow x[n] \\ \text{Quantization : } x[n] \rightarrow \text{digital signals} \end{array} \right.$



T_s : Sampling Period , $f_s = \frac{1}{T_s}$

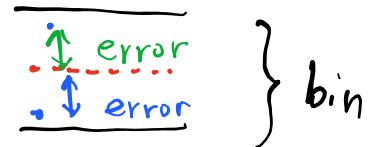
Quantization (e.g., digital images, pixel intensity $0 \sim 255$)

$\underbrace{\hspace{2cm}}$
 8 bits binary representation



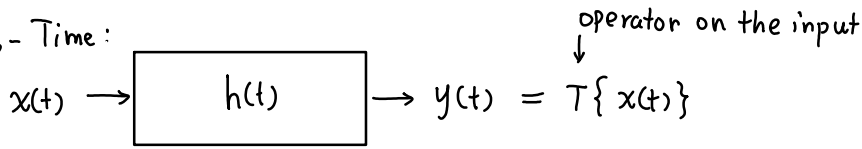
Quantization : real number $\rightarrow k$

Dequantization (reconstruction) $k \rightarrow$ midpoint of the bin



Systems

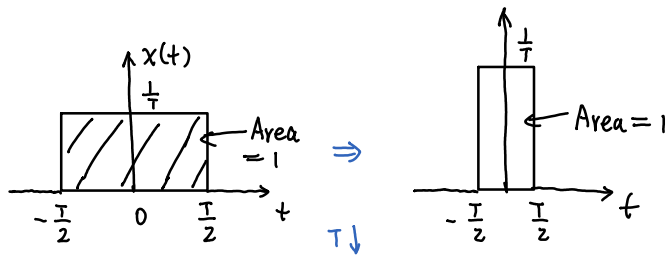
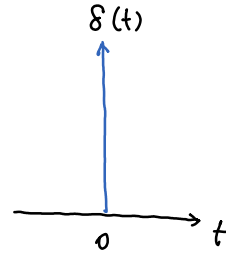
Continuous-Time:



Impulse Response

$$\delta(t) = \begin{cases} \infty, & t = 0 \\ 0, & t \neq 0 \end{cases}$$

$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$

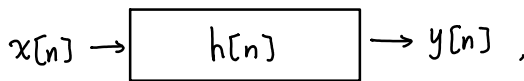


$$h(t) = T\{x(t) = \delta(t)\}$$

Property of impulse signal $\delta(t)$:

$$\int_{-\infty}^{\infty} \delta(t) \cdot \underbrace{s(t)}_{\text{testing function}} dt = s(0)$$

Discrete-Time Systems



$\dots 0, 0, 0, 1, 0, 0, 0, \dots$

$$h[n] = T\{x[n] = \delta[n]\}, \quad \delta[n] = \begin{cases} 1, & n = 0 \\ 0, & n \neq 0 \end{cases}$$

↑
Impulse Response
Sequence

↓
unit impulse sequence

- Linear Time Invariant (LTI) Systems

$$\begin{aligned} y[n] &= x[n] * h[n] &= \sum_{k=-\infty}^{\infty} x[k] \cdot h[n-k] \\ &\quad \uparrow \\ &\quad \text{convolution sum} \\ &= h[n] * x[n] &= \sum_{k=-\infty}^{\infty} h[k] \cdot x[n-k] \end{aligned}$$

- Unit Step Sequence

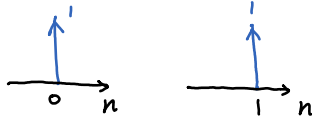
$$u[n] = \begin{cases} 1, & n \geq 0 \\ 0, & n < 0 \end{cases}$$

$$u[n]: \dots 0, 0, 0, 1, 1, 1, 1, \dots$$

$n \quad \dots \quad -2 \quad -1 \quad 0 \quad 1 \quad 2 \quad 3 \quad \dots$
 $\quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \uparrow$

Represent $u[n]$ by using $\delta[n]$,

$$u[n] = \sum_{k=0}^{\infty} \delta[n-k] = \delta[n] + \delta[n-1] + \delta[n-2] + \dots$$



In general, any sequence : $x[n] = \sum_{k=-\infty}^{\infty} x[k] \cdot \delta[n-k]$

$$\begin{aligned}
 &= x[0] \cdot \delta[n] + x[1] \cdot \delta[n-1] \\
 &\quad + x[2] \cdot \delta[n-2] + \dots \\
 &\quad + x[-1] \cdot \delta[n+1] + x[-2] \cdot \delta[n+2] \\
 &\quad + \dots
 \end{aligned}$$

Go back to LTI system:

$$y[n] = T\{x[n]\} = T\left\{ \sum_{k=-\infty}^{\infty} x[k] \cdot \delta[n-k] \right\}$$

Linear :

$$= \sum_{k=-\infty}^{\infty} x[k] \cdot T\{\delta[n-k]\}$$

TI :

$$= \sum_{k=-\infty}^{\infty} x[k] \cdot h[n-k] = x[n] * h[n]$$

Why? $T\{\delta[n]\} = h[n]$

$$T\{\delta[n-k]\} = h[n-k]$$

Exponential Sequences

$$x[n] = |A| \cdot e^{j(\omega_0 n + \phi)} \quad , \quad \text{where } A: \text{Complex number}$$

$$= |A| \cos(\omega_0 n + \phi) + j |A| \sin(\omega_0 n + \phi)$$

e.g., $x[n] = A e^{j\omega_0 n} = A \cos(\omega_0 n) + j A \sin(\omega_0 n)$

↑
Real number

If $\omega_0 = 1$, $y[n] = \sin(n)$

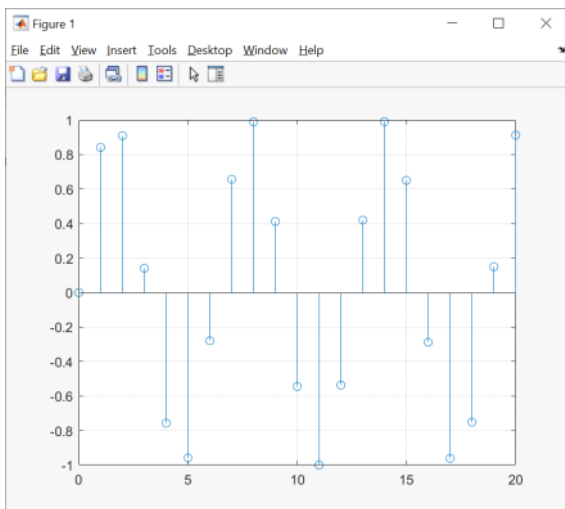
Periodicity: If $y[n]$ is periodic, then $y[n] = y[n+N]$, for all n .

N : period. (integer)

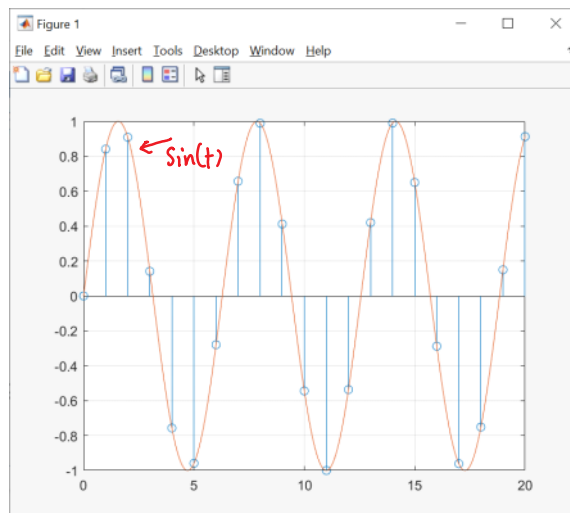
We know that $\sin(t)$ is periodic, since $\sin(t) = \sin(t + 2\pi)$

How about $\sin[n]$, is it periodic?

$\sin[n]$ is not periodic



$\sin(t)$ is periodic



```
>> n = 0: 20;
>> y = sin(n);
>> stem(n, y); grid
```

```
>> t = 0: 0.01: 20;
>> plot(t, sin(t))
```

Another sequence: $x[n] = \cos\left(\frac{\pi}{4}n\right)$

$$= \cos\left(\frac{\pi}{4}n + 2\pi\right) = \cos\left[\frac{\pi}{4}(n+8)\right], \text{ periodic.}$$

↑
 $N = 8$