Lecture 13

Multirate Signal Processing

- Interchange of filtering and compressor



From System (b): $\chi_{b}(e^{j\omega}) = \chi(e^{j\omega}) \cdot H(e^{jM\omega}) \quad \dots \quad (1)$

From System (a): in Lecture II $\xrightarrow{\chi(n)} \downarrow M \longrightarrow \chi_d(n)$ $\chi_d(e^{jw}) = \frac{1}{M} \sum_{i=0}^{M-1} \chi(e^{j(\frac{w}{M} - \frac{2\pi i}{M})})$ Similarly in System (b)

$$\frac{x_{b}[n]}{\sqrt{(e^{jw})}} \xrightarrow{\chi_{b}[n]} \sqrt{M} \xrightarrow{\chi_{b}[n]} \sqrt{(e^{jw})} = \prod_{M} \sum_{i=0}^{M-1} \chi_{b}(e^{j(\frac{w}{M} - \frac{2\pi i}{M})}) \qquad \dots \dots (2)$$

Plugging () into (2):

$$Y(e^{jw}) = \prod_{M} \sum_{i=0}^{M-1} X\left(e^{j\left(\frac{w}{M} - \frac{2\pi i}{M}\right)}\right) H\left(e^{j\left(\frac{w}{M} - \frac{2\pi i}{M}\right)}\right)$$
$$H\left(e^{j\left(w - 2\pi i\right)}\right)$$
$$H\left(e^{j\left(w - 2\pi i\right)}\right)$$
$$= H\left(e^{jw} \cdot e^{-j2\pi i}\right) = H(e^{jw})$$

Thus



- Polyphase Decomposition

$$H(z) \xrightarrow{y[n]} M \xrightarrow{w[n] = y[nM]}$$

More efficient implementation of the above system:



& Apply clownsampling identity



Polyphase Decomposition

$$h[n] = \sum_{k=0}^{M-1} h_k [n-k] = h_0[n] + h_1[n-1] + \dots + h_{M-1}[n-(M-1)]$$

For example $M=2$, then $h[n] = \sum_{k=0}^{2-1} h_k [n-k] = h_0[n] + h_1[n-1]$



In general, $e_{k}[n] = h_{k}[nM]$



Figure 4.35 Polyphase decomposition of filter h[n] using components $e_{\kappa}[n]$.



Figure 4.36 Polyphase decomposition of filter h[n] using components $e_k[n]$ with chained delays.



$$\begin{split} h(\mathbf{n}) &= \sum_{k=0}^{M-1} h_{k} [n-k] \\ \downarrow \not\subseteq T \\ H(z) &= \sum_{k=0}^{M-1} \vec{z} \left\{ h_{k} [n-k] \right\} = \sum_{k=0}^{M-1} H_{k}(z) \cdot \vec{z}^{-k} \quad \dots \dots (l) \\ \\ where \quad h_{k} [n] \quad \overrightarrow{zT} \rightarrow H_{k}(z) \cdot \vec{z}^{-k} \quad \text{Time-Shift Property of } \vec{z}^{-T} \\ \\ h_{k} [n-k] \quad \overrightarrow{zT} \rightarrow H_{k}(z) \cdot \vec{z}^{-k} \quad \text{Time-Shift Property of } \vec{z}^{-T} \\ \\ Now, \quad e_{k} [n] = h_{k} [nM] \\ \downarrow \not\in T \\ \\ E_{k}(z) = \sum_{n=-\infty}^{\infty} e_{k} [n] \cdot \vec{z}^{-n} = \sum_{n=-\infty}^{\infty} h_{k} [nM] \cdot \vec{z}^{-n} \\ \\ \\ \text{Thus} \quad E_{k} (\vec{z}^{M}) = \sum_{n=-\infty}^{\infty} h_{k} [nM] \cdot \vec{z}^{-k} \frac{\pi}{s} \\ \\ \text{Let} \quad s = nM , \quad E_{k} (\vec{z}^{M}) = \sum_{s=-\infty}^{\infty} h_{k} [s] \cdot \vec{z}^{-s} = H_{k}(z) \\ \\ \\ \text{Therefore} \quad E_{k}(\vec{z}^{M}) = H_{k}(z) \\ \\ \\ B_{j} \quad E_{q}(l) : \qquad H(z) = \sum_{k=0}^{M-1} H_{k}(z) \cdot \vec{z}^{-k} \\ \\ \\ Hence \qquad H(\vec{z}) = \sum_{k=0}^{M-1} E_{k} (\vec{z}^{M}) \cdot \vec{z}^{-1} + E_{2} (\vec{z}^{M}) \cdot \vec{z}^{-2} + \dots E_{q} (\vec{z}^{M}) \cdot \vec{z}^{-k+n} \\ \\ \\ \end{array}$$

$$H(z) = \sum_{k=0}^{M-1} E_{k}(z^{M}) \cdot z^{-k}$$

= $E_{0}(z^{M}) + E_{1}(z^{M}) \cdot z^{-1} + E_{2}(z^{M}) \cdot z^{-2} + \cdots + E_{M-1}(z^{M}) \cdot z^{-(M-1)}$



Figure 4.37 Realization structure based on polyphase decomposition of h[n].

Equivalent to : $\chi[n] \rightarrow H(z) \rightarrow y[n)$



Comparison of computational complexity

Direct Implementation



Input x[n] is clocked at a rate of one sample per unit time and H(z) N-point FIR filter

of Multiplications (mults): N # of Additions (adds): (N-1)

Implementation of the decimation filter with polyphase decomposition



Each of the filter $E_{k}(t)$ is of length N/M, and their inputs are clocked at a rate of 1 per M units of time.

of Multiplications (mults): (1/M)x(N/M)
of Additions (adds): (1/M)x(N/M - 1)

Since there are M polyphase filters, so the total

of Multiplications (mults): $M \times (1/M) \times (N/M) = N/M \ll N$ # of Additions (adds): $M \times (1/M) \times (N/M - 1) + (1/M) \times (M-1) = \frac{N}{M} \sim I + \frac{M-I}{M} \ll N-I$