## Lecture 16

- All-Pass Systems

$$Hap(z) = \frac{z^{-1} - a^{*}}{1 - az^{-1}}, \quad a^{*} \text{ is the conjugate of a.}$$

$$= \frac{z}{z} \cdot \frac{z^{-1} - a^{*}}{1 - az^{-1}} = \frac{1 - a^{*}z}{z - a} = \frac{-a^{*}(z - \frac{1}{a^{*}})}{z - a}$$

$$\text{Zero: } \frac{1}{a^{*}}$$

$$\text{pole: } a \quad \Rightarrow \frac{\left(\frac{1}{1}\text{Pole}\right)^{+} \rightarrow \text{pole}}{\left(\frac{1}{\text{pole}}\right)^{+} \rightarrow \text{zero}}$$

$$z = e^{j\omega}$$

$$\text{Hap}(e^{j\omega}) = \frac{e^{-j\omega} - a^{*}}{1 - ae^{-j\omega}} = \frac{e^{-j\omega}(1 - a^{*}e^{j\omega})}{1 - ae^{-j\omega}}$$

$$|\text{Hap}(e^{j\omega})| = \frac{|e^{-j\omega}| \cdot |1 - a^{*}e^{j\omega}|}{|1 - ae^{-j\omega}|} = 1$$

$$\text{Why?}$$

$$|e^{-j\omega}| = 1$$

$$\text{Let } A = 1 - a^{*}e^{j\omega}, \quad \text{then } A^{*} = 1 - (a^{*}e^{j\omega})^{*} = 1 - ae^{-j\omega}$$

$$|x + jy| = |x - jy| \text{ in general}$$

- General Form of All-Pass Systems

$$H_{ap}(z) = A \prod_{k=1}^{Mr} \frac{z^{-1} - d_k}{1 - d_k z^{-1}} \prod_{k=1}^{Mc} \frac{z^{-1} - e_k^*}{1 - e_k z^{-1}} \cdot \frac{z^{-1} - e_k}{1 - e_k^* z^{-1}}$$

$$d_k's : real poles$$

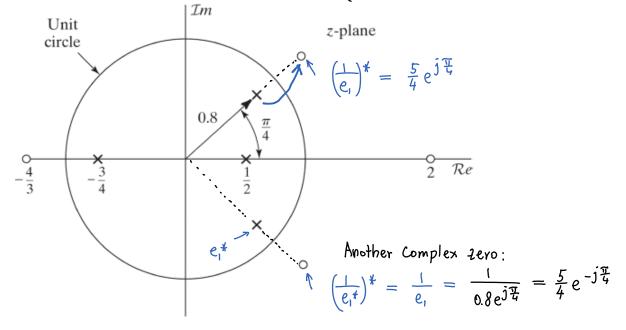
$$e_k's : complex poles$$

$$e_k''s : complex poles$$

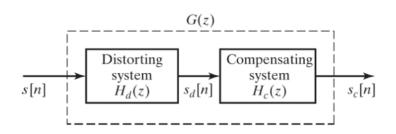
Example: 
$$M_r = 2$$
,  $d_1 = \frac{1}{2}$ ,  $d_2 = -\frac{3}{4}$  Two real zeros:  $\left(\frac{1}{2} = 2\right)$ 

Two real poles,  $d_1 = \frac{1}{2}$ ,  $d_2 = -\frac{3}{4}$  Two real zeros:  $\left(\frac{1}{2} = -\frac{4}{3}\right)$ 
 $M_c = 1$ ,  $e_1 = 0.8 e^{j\frac{\pi}{4}}$ ,  $e_1^{\dagger} = 0.8 e^{-j\frac{\pi}{4}}$ 

Two complex zeros:  $\left(\frac{1}{e_1}\right)^* = \left(\frac{1}{0.8 e^{j\frac{\pi}{4}}}\right)^* = \left(\frac{5}{4} e^{-j\frac{\pi}{4}}\right)^* = \frac{5}{4} e^{j\frac{\pi}{4}}$ 



Application: Distortion Compensation by Linear Filtering



$$G(t) = Hap(t) = 1$$

H<sub>1</sub>(7): non-minimum-phase system

One option: 
$$G(z) = Hd(z) \cdot H_c(z) = I \Rightarrow H_c(z) = \frac{I}{Hd(z)}$$
Inverse System of Hd(z)

Second Option: What if 
$$Hd(z) = Hd_{min}(z) \cdot Hap(z)$$
?

not minimum-phase minimum-phase all-pass system

Then we can choose the corresponding filter to be Compensating

$$H_{c}(z) = \frac{1}{Hd_{min}(z)}$$

Such that

$$G(z) = H_{d}(z) \cdot H_{c}(z) = H_{d_{min}}(z) \cdot H_{\alpha\rho}(z) \cdot \frac{1}{H_{d_{min}}(z)} = H_{\alpha\rho}(z)$$

Example: Decomposition of a non-minimum-phase system as a minimum-phase system, followed by an all-pass system.

$$H(z) = \frac{1+3z^{-1}}{1+\frac{1}{2}z^{-1}} = \frac{z+3}{z+\frac{1}{2}}$$
 *Iero*: -3 (outside the unit circle)

non-minimum-phase

Goal: 
$$H(z) = H_{min}(z) \cdot H_{ap}(z)$$

In general, H(Z) has a zero C\* outside the unit circle

Move the zero C\* to the all-pass system Hap(Z)

Pair up the newly introduced zero C\* with a new pole:  $\left(\frac{1}{c^*}\right)^* = \frac{1}{c}$ .

Compensate for this new pole with a zero at  $\frac{1}{C}$ and put this zero into  $H_{min}(z)$ †
inside the unit circle inside the unit circle

## Compared with

$$H_{ap}(z) = \frac{z^{-1} - a^{*}}{1 - a^{2}}$$

$$|H_{ap}(z)| = 1$$

Hap (=) in the above example:

$$= \frac{1 + 3t^{-1}}{1 + \frac{1}{3}t^{-1}}$$

$$= \frac{3(t^{-1} + \frac{1}{3})}{1 - (-\frac{1}{3})t^{-1}}$$

$$\left| \frac{1 + 3z^{-1}}{1 + \frac{1}{3}z^{-1}} \right| = 3 \cdot \left| \frac{z^{-1} - \left(-\frac{1}{3}\right)}{1 - \left(-\frac{1}{3}\right)z^{-1}} \right|$$

$$= 3$$

All-pass system with |Hap(z)| = 3

$$H(z) = 3 \cdot \frac{1 + \frac{1}{3}z^{-1}}{1 + \frac{1}{2}z^{-1}} \cdot \frac{z^{-1} + \frac{1}{3}}{1 + \frac{1}{3}z^{-1}}$$

$$H_{min}(z) \qquad H_{ap}(z) = 1$$
and  $|H_{ap}(z)| = 1$ 

Another Example:

$$H(z) = \frac{\left(1 + \frac{3}{2}e^{j\frac{\pi}{4}}z^{-1}\right)\left(1 + \frac{3}{2}e^{-j\frac{\pi}{4}}z^{-1}\right)}{1 - \frac{1}{3}z^{-1}} = H_{min}(z) \cdot H_{ap}(z)$$

Two zeros:  $-\frac{3}{2}e^{j\frac{\pi}{4}}$ ,  $-\frac{3}{2}e^{-j\frac{\pi}{4}}$  both are outside the unit circle.

One pole:  $\frac{1}{3}$  (inside the unit circle)

$$H(z) = \frac{?}{1 - \frac{1}{3} z^{-1}} \cdot \frac{?}{?}$$

$$H_{ao}(z)$$

Align with the form:  $H_{ap}(z) = \frac{z^{-1} - a^*}{1 - a^* - a^*}$ 

$$|+\frac{3}{2}e^{j\frac{\pi}{4}}\xi^{-1}| = \frac{3}{2}e^{j\frac{\pi}{4}}\left(\xi^{-1} + \frac{1}{\frac{3}{2}e^{j\frac{\pi}{4}}}\right) = \frac{3}{2}e^{j\frac{\pi}{4}}\left[\xi^{-1} - \left(-\frac{2}{3}e^{-j\frac{\pi}{4}}\right)\right]$$
moved to Hmin(\vartex)

$$|+\frac{3}{2}e^{j\frac{\pi}{4}}z^{-1}| = \frac{3}{2}e^{j\frac{\pi}{4}}\left(z^{-1} + \frac{1}{\frac{3}{2}e^{j\frac{\pi}{4}}}\right) = \frac{3}{2}e^{j\frac{\pi}{4}}\left[z^{-1} - \left(-\frac{2}{3}e^{j\frac{\pi}{4}}\right)\right]$$
Thus

Thus
$$Hap(\bar{z}) = \frac{\left[ \bar{z}^{-1} - \left( -\frac{2}{3} \cdot e^{-j\frac{\pi}{4}} \right) \right] \cdot \left[ \bar{z}^{-1} - \left( -\frac{2}{3} \cdot e^{j\frac{\pi}{4}} \right) \right]}{\left[ 1 - \left( -\frac{2}{3} e^{j\frac{\pi}{4}} \right) \bar{z}^{-1} \right] \cdot \left[ 1 - \left( -\frac{2}{3} e^{-j\frac{\pi}{4}} \right) \bar{z}^{-1} \right]}$$

$$\left( -\frac{2}{3} e^{-j\frac{\pi}{4}} \right)^{*} \qquad \left( -\frac{2}{3} e^{j\frac{\pi}{4}} \right)^{*}$$

$$H_{a_{p}}(z) = \frac{\left(z^{-1} + \frac{2}{3}e^{-j\frac{\pi}{4}}\right)\left(z^{-1} + \frac{2}{3}e^{j\frac{\pi}{4}}\right)}{\left(1 + \frac{2}{3}e^{j\frac{\pi}{4}}z^{-1}\right)\left(1 + \frac{2}{3}e^{-j\frac{\pi}{4}}z^{-1}\right)}$$
And

And

And
$$H_{min}(z) = \frac{(1+\frac{2}{3}e^{j\frac{\pi}{4}}z^{-1})(1+\frac{2}{3}e^{-j\frac{\pi}{4}}z^{-1})}{1-\frac{1}{3}z^{-1}} \cdot \frac{3}{2}e^{j\frac{\pi}{4}} \cdot \frac{3}{2}e^{-j\frac{\pi}{4}}$$

In summary,

$$H(z) = \frac{\left(1 + \frac{3}{2}e^{j\frac{\pi}{4}}z^{-1}\right)\left(1 + \frac{3}{2}e^{-j\frac{\pi}{4}}z^{-1}\right)}{1 - \frac{1}{3}z^{-1}} = H_{min}(z) \cdot H_{ap}(z)$$

where

$$H_{min}(z) = \frac{9}{4} - \frac{(1 + \frac{2}{3}e^{j\pi}z^{-1})(1 + \frac{2}{3}e^{-j\pi}z^{-1})}{1 - \frac{1}{3}z^{-1}}$$

$$H_{a_{p}}(z) = \frac{\left(z^{-1} + \frac{2}{3}e^{-j\frac{\pi}{4}}\right)\left(z^{-1} + \frac{2}{3}e^{j\frac{\pi}{4}}\right)}{\left(1 + \frac{2}{3}e^{j\frac{\pi}{4}}z^{-1}\right)\left(1 + \frac{2}{3}e^{-j\frac{\pi}{4}}z^{-1}\right)}$$