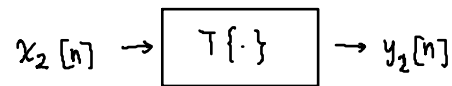
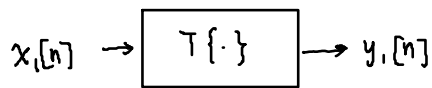


Lecture 2

- Linear / Non-linear Systems



$$ax_1[n] + bx_2[n] \rightarrow \boxed{T\{\cdot\}} \stackrel{?}{\rightarrow} ay_1[n] + by_2[n]$$

$$\text{If } T\{ax_1[n] + bx_2[n]\} = aT\{x_1[n]\} + bT\{x_2[n]\}$$

for all a and b , then the system is linear.

Example: $y[n] = \sum_{k=-\infty}^n x[k]$ Accumulator System

$$y_1[n] = \sum_{k=-\infty}^n x_1[k], \quad y_2[n] = \sum_{k=-\infty}^n x_2[k]$$

$$x_3[n] = ax_1[n] + bx_2[n]$$

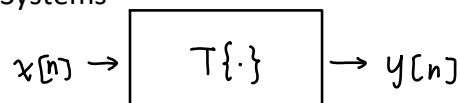
$$y_3[n] = \sum_{k=-\infty}^n x_3[k] = \sum_{k=-\infty}^n \{ax_1[k] + bx_2[k]\}$$

$$= a \sum x_1[k] + b \sum x_2[k]$$

$$= ay_1[n] + by_2[n]$$

The system is linear.

- Time-Invariant (TI) Systems



$$x_1[n] = x[n - n_0] \rightarrow$$

↑
Arbitrary
integer $\neq 0$

$$\rightarrow y_1[n] \stackrel{?}{=} y[n - n_0]$$

If "=" then

Shift-invariant or T-I

Example: $y[n] = \sum_{k=-\infty}^n x[k]$

$$x_1[n] = x[n - n_0], \quad y_1[n] = \sum_{k=-\infty}^{\infty} x_1[k] = \sum_{k=-\infty}^{\infty} x[\underbrace{k - n_0}_{k_1}]$$

Let $k_1 = k - n_0$

Since $-\infty \leq k \leq n$, $-\infty \leq k_1 = k - n_0 \leq n - n_0$

$$y_1[n] = \sum_{k_1=-\infty}^{n-n_0} x[k_1] = y[n - n_0] = \sum_{k=-\infty}^{n-n_0} x[k]$$

Since $y[n] = \sum_{k=-\infty}^n x[k]$

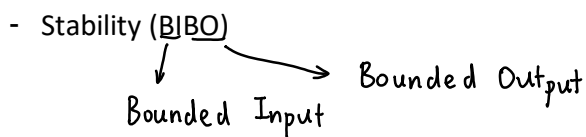
Yes, the system is T-I.

Another example: $y[n] = x[2n]$

$$x_1[n] = x[n - n_0], \quad y_1[n] = x_1[2n] = x[2n - n_0] = x[2(n - \frac{n_0}{2})]$$

Check if $y_1[n] \stackrel{?}{=} y[n - n_0] = x[2(n - n_0)]$
 \neq

Hence, the system is Time-Variant (NOT T-I).



If $|x[n]| \leq B_x$, and $|y[n]| \leq B_y$, both B_x and $B_y < \infty$

then the system is stable.

Example: $y[n] = \{x[n]\}^2 \quad \forall n$ (for all n values)

If $|x[n]| \leq B_x$, $|y[n]| = |(x[n])^2| = \{|x[n]|\}^2 \leq B_x^2 = B_y$

Yes, stable.

Another example: $y[n] = \sum_{k=-\infty}^n x[k]$ non-stable.

Pick an input $x[n] = u[n]$, $|u[n]| \leq 1$, $y[n] = \sum_{k=-\infty}^n u[k] = \begin{cases} 0, & n < 0 \\ n+1, & n \geq 0 \end{cases}$
 $n \rightarrow \infty$, $y[n] = n+1 \rightarrow \infty$

- Causality

If the output of the system depends on the current or previous inputs only, then the system is causal.

Example : $y[n] = x[n] - x[n-1]$ Causal

\uparrow \uparrow \uparrow
 Current Current previous input

$y[n] = x[n+1] - x[n]$ non-causal

\uparrow
 future

- Convolution Sum

- Linear Time Invariant (LTI) Systems

$h[n] = T\{\delta[n]\}$

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] \cdot h[n-k]$$

\uparrow
Convolution sum

$$= h[n] * x[n] = \sum_{k=-\infty}^{\infty} h[k] \cdot x[n-k]$$

Interpretation of Convolution Sums

- Superposition

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] \cdot h[n-k]$$

\downarrow → sequence (a shifted version of $h[n]$)
 $x[k] : \text{const}$

$$= x[0] \cdot h[n] + x[1] \cdot h[n-1] + x[2] \cdot h[n-2] + \dots$$

$$+ x[-1] \cdot h[n+1] + x[-2] \cdot h[n+2] + \dots$$

- Computational (flipping, shifting)

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] \cdot h[n-k]$$

\downarrow shifting
 $h[-(k-n)]$
 \uparrow flipping

Flipping example : $z[n] = \{ \dots, -3, -2, -1, 0, 1, 2, 3, \dots \}$

$n \Rightarrow \begin{matrix} \uparrow & \uparrow & \uparrow & \uparrow & \uparrow & \uparrow & \uparrow \\ -3 & -2 & -1 & 0 & 1 & 2 & 3 \end{matrix}$

$z[n] = \{ \dots, 3, 2, 1, 0, -1, -2, -3, \dots \}$

$z[n-1] = \{ \dots, -3, -2, -1, 0, 1, 2, \dots \}$

\uparrow
 Shifted version of $z[n]$
 delayed by one time point

Example 2.11 (pp 27)

$$h[n] = u[n] - u[n-N] = \begin{cases} 1, & 0 \leq n \leq N-1 \\ 0, & \text{elsewhere} \end{cases}$$

e.g., $N=2$

$u[n] - u[n-2]$	$\dots -3 \ -2 \ -1 \ 0 \ 1 \ 2 \ \dots$	n
	$\dots 0, 0, 0, 1, 1, 1, \dots$	$u[n]$
	$\dots 0, 0, 0, 0, 0, 1, 1, \dots$	$u[n-2]$
$= \begin{cases} 1, & 0 \leq n \leq 2-1=1 \\ 0, & \text{elsewhere} \end{cases}$	$0, 0, 0, 1, 1, 0, 0, \dots$	$u[n] - u[n-2]$

Input $x[n] = a^n u[n] = \begin{cases} a^n, & n \geq 0 \\ 0, & \text{elsewhere} \end{cases}$

e.g., $a = 0.5$, $x[n] = \dots -2 \ -1 \ 0 \ 1 \ 2 \ \dots \ n$
 $\dots 0, 0, 0, 1, 0.5, 0.25, \dots$

Derivation : $y[n] = \sum_{k=-\infty}^{\infty} x[k] \cdot h[n-k]$

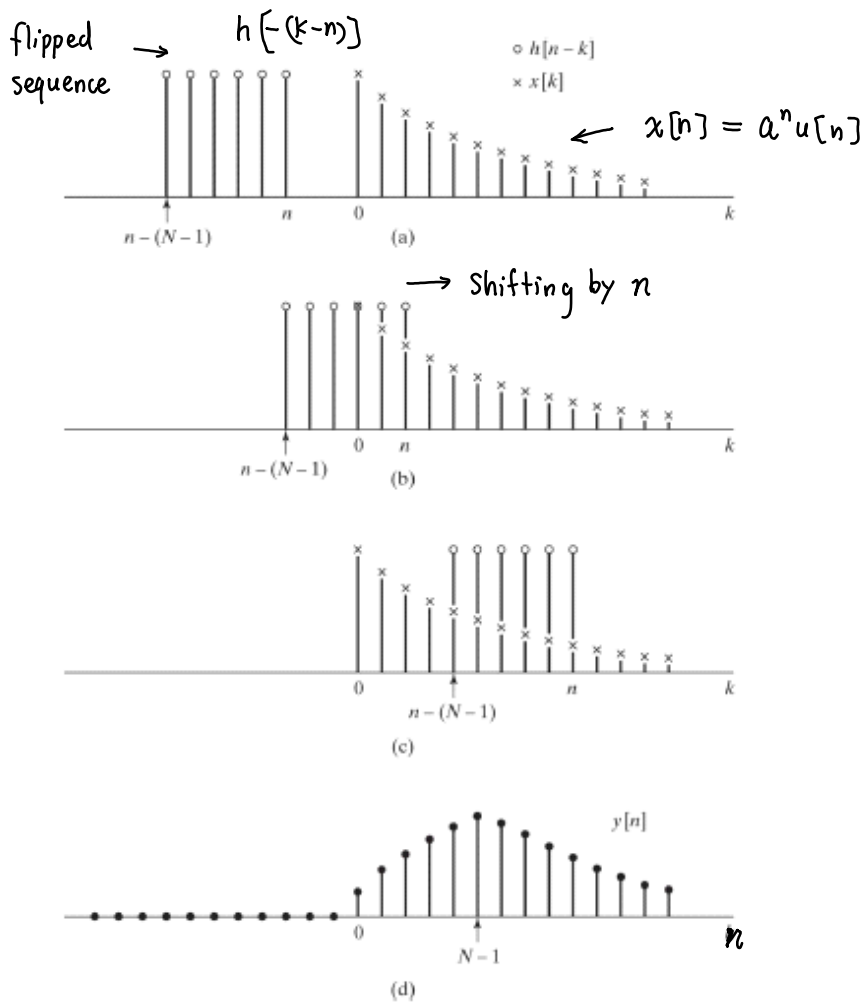
focus on $h[n-k] \neq 0$

For $h[n-k] = 1$, $0 \leq n-k \leq N-1$

$$\Rightarrow \begin{cases} k \leq n \\ k \geq n - (N-1) \Rightarrow k \geq n - N + 1 \end{cases}$$

$$\Rightarrow n - N + 1 \leq k \leq n$$

How about $x[k]$? $k \geq 0$, $x[k] \neq 0$; otherwise $x[k] = 0$



Derivation (algebraic) (cont'd) :

$$\begin{cases} 0 \leq k \\ n-N+1 \leq k \leq n \end{cases} \Rightarrow \max(0, n-N+1) \leq k \leq n$$

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] \cdot h[n-k]$$

Cases :

(1) $n < 0$, $\overbrace{\max(0, n-N+1)}^0 \leq k \leq n < 0$

$$x[k] \cdot h[n-k] = 0, \quad y[n] = 0$$

(2) $0 < n \leq N-1$, $\underbrace{n-(N-1)}_{\rightarrow} \leq 0$, thus $\max(0, n-(N-1)) = 0$

Thus $0 \leq k \leq n \leq N-1$

$$\begin{aligned}
 y[n] &= \sum_{k=-\infty}^{\infty} x[k] \cdot h[n-k] \\
 &= \sum_{k=0}^n x[k] \cdot 1 = \sum_{k=0}^n a^k = 1 + a + a^2 + \dots + a^n \\
 &\quad \text{geometric series} \quad = \frac{1(1-a^{n+1})}{1-a} = \frac{1-a^{n+1}}{1-a}.
 \end{aligned}$$

$$(3) \quad n > N-1 \Rightarrow n - (N-1) > 0 \Rightarrow \max(0, n - (N-1)) = n - (N-1)$$

$$\text{Thus} \quad n - (N-1) \leq k \leq n$$

$$y[n] = \sum_{k=n-(N-1)}^n a^k \cdot 1 = \frac{a^{n-N+1} - a^{n+1}}{1-a}.$$

$$\text{In general,} \quad \sum_{k=N_1}^{N_2} a^k = \frac{a^{N_1} - a^{N_2+1}}{1-a}, \quad N_2 \geq N_1$$

In Summary

$$y[n] = \begin{cases} 0, & n < 0 \\ \frac{1-a^{n+1}}{1-a}, & 0 \leq n \leq N-1 \\ a^{n-N+1} \left(\frac{1-a^N}{1-a} \right), & n > N-1 \end{cases}$$

- Matlab function conv()

```

>> n = 0: 20;
>> x = (0.5).^n;
>> h = [1, 1, 1, 1];
>> y = conv(x, h);
>> stem(y); grid

```

