## The University of Alabama in Huntsville ECE Department EE 202 – 02 May 2, 2014 Final Exam

Name: \_\_\_\_\_

J	Κ	Q(t+1)
0	0	Q(t)
0	1	0
1	0	1
1	1	Q'(t)

D	Q(t+1)
0	0
1	1

Т	Q(t+1)
0	Q(t)
1	Q'(t)

- 1. (1 point).\_\_\_\_\_ is a controlling value for a NAND gate.
- 2. (1 point) \_\_\_\_\_ (True/False) Flip-flops are level sensitive.
- 3. (1 point) \_\_\_\_\_ (True/False) When finding the sum-of-products form for a circuit, the procedure is to start with the 1's in a K-map.
- 4. (1 point) A \_\_\_\_\_\_ state machine has outputs that depend only on the state.
- 5. (1 point) A \_\_\_\_\_ is a group of binary cells.
- 6. (5 points Convert (64013.25<sub>8</sub>) to decimal:

7. (10 points) Convert decimal -83 and -62 to binary, using 8-bit signed-2's-complement representation. Then perform the binary equivalent of (-83) + (-62). Convert the answer back to decimal and verify that it is correct or explain why it is not.

8. (10 points) How many 4 x 1 multiplexers does it take to construct a 64 x 1 multiplexer?

9. (15 points) A traffic metering system for controlling the release of traffic from an entrance ramp onto a superhighway has the following specifications for a part of its controller. There are three parallel metering lanes, each with its own stop (red) – go (green) light. One of these lanes, the car pool lane, is given priority for a green light over the other two lanes. Otherwise, a "round robin" scheme in which the green lights alternate is used for the other two (left and right) lanes. The part of the controller that determines which light is to be green (rather than red) is to be designed. The specifications for the controller follow:

Inputs:

- PS Car pool lane sensor (car present 1; car absent 0)
- LS Left lane sensor (car present 1; car absent 0)
- RS Right lane sensor (car present 1; car absent 0)
- RR Round robin signal (select left 1; select right 0)

Outputs:

- PL Car pool lane light (green 1; red 0)
- LL Left lane light (green 1; red 0)
- RL Right lane light (green 1; red 0)

Operation:

- 1. If there is a car in the car pool lane, PL is 1.
- 2. If there are no cars in the car pool lane and the right lane, and there is a car in the left lane, LL is 1.
- 3. If there are no cars in the car pool lane and in the left lane, and there is a car in the right lane, RL is 1.
- 4. If there is no car in the car pool lane, there are cars in both the left and right lanes, and RR is 1, then LL = 1.
- 5. If there is no car in the car pool lane, there are cars in both the left and right lanes, and RR is 0, then RL = 1.
- 6. If any PL, LL, or RL is not specified to be 1 above, then it has value 0.

Design this controller circuit, including developing a truth table, using K-maps to minimize, and drawing a circuit diagram.

10. (5 points) If a coding system is needed to represent the number of students at UAH (7700), how many bits are required?

11. (5 points) Write out the truth table for a 3-input exclusive-OR gate that has the inputs A, B, and C, and one output, F.

12. (15 points) Construct a 5-to-32 line decoder using only 3-to-8 line decoders with enable. If necessary, configure a 3-to-8 line decoder to represent any additional logic needed. Use block diagrams for the components.

13. (15 points) Design a 3-bit counter which counts in the sequence 000, 001, 010, 011, 100, 101, 000, using clocked D flip-flops. You do not have to draw the circuit diagram. Is the counter self-correcting if it comes up in an unused state?

14. (15 points) A synchronous sequential circuit has one input and one output plus a synchronous reset which is active low. If the input sequence 1001 or 0101 occurs, an output of two successive 1s will occur. The first of these 1s should occur coincident with the last input of the 1001 or 0101 sequence. The network should reset when the second 1 output occurs. For example,

 Input sequence:
 01101100010010 1101010

 Output sequence:
 0000000000011 0000011

Draw a Mealy state diagram for this circuit. Do not include the reset in your diagram.