



**CPE 323 Introduction to
Embedded Computer Systems:
MSP430: Assembly Language and C**

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Lecture Notes



Outline

- **Assembly Language Programming**
 - Adding two 32-bit numbers (decimal, integers)
 - Counting characters 'E'
- **Subroutines**
 - CALL&RETURN
 - Subroutine Nesting
 - Passing parameters
 - Stack and Local Variables
- **C and the MSP430**



Assembly Language Programming: Decimal/Integer Addition of 32-bit Numbers

- Problem

- Write an assembly program that finds a sum of two 32-bit numbers
 - Input numbers are decimal numbers (8-digit in length)
 - Input numbers are signed integers in two's complement

- Data:

- lint1: DC32 0x45678923
- lint2: DC32 0x23456789
- Decimal sum: 0x69135712
- Integer sum: 0x68adf0ac

- Approach

- Input numbers: storage, placement in memory
- Results: storage (ABSOLUTE ASSEMBLER)
- Main program: initialization, program loops
- Decimal addition, integer addition



Decimal/Integer Addition of 32-bit Numbers

```
/*-----  
* Program      : Program demonstrates addition of two operands lint1 and lint2.  
*              : Operands are first interpreted as 32-bit decimal numbers and  
*              : and their sum is stored into lsumd;  
*              : Next, the operands are interpreted as 32-bit signed integers  
*              : in two's complement and their sum is stored into lsumi.  
* Input       : Input integers are lint1 and lint2 (constants in flash)  
* Output      : Results are stored in lsumd (decimal sum) and lsumi (int sum)  
* Written by  : A. Milenkovic  
* Date       : September 10, 2008; Updated September 14, 2009  
* Description: MSP430 IAR EW; Demonstration of the MSP430 assembler  
*-----*/  
  
#include "msp430.h"                ; #define controlled include file  
  
        NAME      main              ; module name  
  
        PUBLIC   main                ; make the main label visible  
                                ; outside this module  
        ORG      0xF000              ; move location pointer to 0xF000  
lint1:   DC32    0x45678923          ; operand1  
lint2:   DC32    0x23456789          ; operand2  
  
        ORG      0xFFFFE            ; set reset vector to 'init' label  
        DC16     main  
  
        ORG      0x0400  
lsumd:   DS32    1                   ; allocates space for lsumd (2 words)  
lsumi:   DS32    1                   ; allocate space for lsumi (2 words)
```



Decimal/Integer Addition of 32-bit Numbers (cont'd)

```

                ORG 0xE000                ; starting address of the program
main:          NOP                       ; main program
                MOV.W  #WDTPW+WDTHOLD,&WDTCTL ; Stop watchdog timer
                MOV #lint1, R4           ; pointer to lint1
                MOV #lsumd, R8           ; pointer to lsumd (decimal sum)
                MOV #2, R5               ; R5 is a counter (2 words)
                CLR R10                  ; clear R10 (used as a backup for SR)
ldeca:        MOV 4(R4), R7              ; load lint2 (@R4+4) into R7
                MOV R10, R2              ; bring original R2
                DADD @R4+, R7            ; decimal add to lint1 (@R4)
                MOV R2, R10              ; backup R2 in R10
                MOV R7, 0(R8)            ; store result back into lsumd
                ADD #2, R8                ; R8 points to the next word in lsumd
                DEC R5                    ; decrement R5
                JNZ ldeca                 ; jump if not zero to ldeca
```



Decimal/Integer Addition of 32-bit Numbers (cont'd)

```
MOV #lint1, R4           ; pointer to lint1
MOV #lsumd, R8           ; pointer to lsumd
MOV #2, R5                ; R5 is a counter
CLR R10                  ; clear R10
lia: MOV 4(R4), R7         ; load lint2
MOV R10, R2              ; load original SR
ADDC @R4+, R7            ; add lint1 (with carry)
MOV R2, R10              ; backup R2 in R10
MOV R7, 4(R8)            ; store result into lsumi (@R8+4)
ADD #2, R8               ; update R8
DEC R5                   ; decrement R5
JNZ lia                  ; jump if not zero to lia

JMP $                    ; jump to current location '$'
                           ; (endless loop)

END
```



Assembly Language Directives

```
        ORG 0xF000
b1:     DB    5          ; allocates a byte in memory and initialize it with constant 5;
                          ; equivalent to DC8 5
b2:     DB   -122       ; allocates a byte with constant -122
b3:     DB   10110111b  ; binary value of a constant
b4:     DB   0xA0       ; hexadecimal value of a constant
b5:     DB   123q       ; octal value of a constant
        EVEN          ; move a location pointer to the first even address
tf      EQU 25

w1:     DW   32330      ; allocates a a word size constant in memory;
                          ; equivalent to DC16 32330
w2:     DW  -32000
dw1:    DL  100000      ; allocates a long word size constant in memory;
                          ; equivalent to DC32 100000
dw2:    DL  -10000
dw3:    DL 0xFFFFFFFF
dw4:    DL tf
s1:     DB 'ABCD'      ; allocates 4 bytes in memory with string ABCD
s2:     DB "ABCD"     ; allocates 5 bytes in memory with string ABCD
                          ; and \0 character at the end
```



Assembly Language Directives (cont'd)

```
ORG 0x0200
v1b DS 1 ; allocates a byte in memory; equivalent to DS8
v2b DS 1 ; allocates a byte in memory;
v3w DS 2 ; allocates a word of 2 bytes in memory;
      ; equivalent to DS8 2 or DS16
v4b DS32 4 ; allocates a buffer of 4 long words;
      ; 4x4=16 bytes in memory
```




Assembly Language Programming: Count Characters 'E'

- Problem

- Write an assembly program that processes an input string to find the number of characters 'E' in the string
- The number of characters is “displayed” on the port 1 of the MSP430

- Example:

- `mystr="HELLO WORLD, I AM THE MSP430!"`
- `P1OUT=0x02`

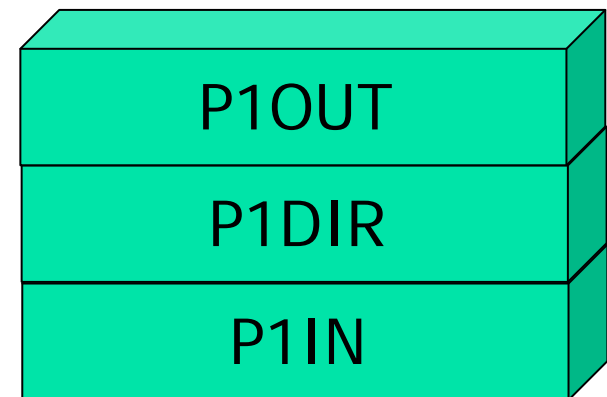
- Approach

- Input string: storage, placement in memory
- Main program: initialization, main program loop
- Program loop: iterations, counter, loop exit
- Output: control of ports

Programmer's View of Parallel Ports

- Six parallel ports: $x=1,2,3,4,5,6$
- Each can be configured as:
 - Input: $PxDIR=0x00$ (default)
 - Output: $PxDIR=0xFF$
- Writing to an output port:
 - $PxOUT=x02$
- Reading from an input port:
 - $My_port=P1IN$

Port Registers





Count Characters 'E'

```
/*-----  
* Program      : Counts the number of characters E in a string  
* Input        : The input string is the myStr  
* Output       : The port one displays the number of E's in the string  
* Written by   : A. Milenkovic  
* Date        : August 14, 2008  
* Description: MSP430 IAR EW; Demonstration of the MSP430 assembler  
*-----*/  
  
#include "msp430.h"                ; #define controlled include file  
  
NAME      main                    ; module name  
PUBLIC    main                    ; make the main label visible  
                                ; outside this module  
  
ORG       0FFFFh  
DC16     init                     ; set reset vector to 'init' label  
  
RSEG     CSTACK                   ; pre-declaration of segment CSTACK  
RSEG     CODE                     ; place program in 'CODE' segment
```



Count Characters 'E' (cont'd)

```
init:    MOV        #SFE(CSTACK), SP
        ; set up stack
```

```
main:    NOP
        ; main program
        MOV.W
#WDTPW+WDTHOLD,&WDTCTL    ; stop
watchdog timer
        BIS.B    #0FFh,&P1DIR
        ; configure P1.x output
```



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- Assembly Language Programming
 - Adding two 32-bit numbers (decimal, integers)
 - Counting characters 'E'
- Subroutines
 - CALL&RETURN
 - Subroutine Nesting
 - Passing parameters
 - Stack and Local Variables
- C and the MSP430



The Case for Subroutines: An Example

- Problem
 - Sum up elements of two integer arrays
 - Display results on P2OUT&P1OUT and P4OUT&P3OUT
- Example
 - arr1 DC16 1, 2, 3, 4, 1, 2, 3, 4 ; the first array
 - arr2 DC16 1, 1, 1, 1, -1, -1, -1 ; the second array
 - Results
 - P2OUT&P1OUT=0x000A, P4OUT&P3OUT=0x0001
- Approach
 - Input numbers: arrays
 - Main program (no subroutines):
initialization, program loops



Sum Up Two Integer Arrays (ver1)

```
/*-----  
* Program      : Find a sum of two integer arrays;  
* Input        : The input arrays are signed 16-bit integers in arr1 and arr2  
* Output       : Display sum of arr1 on P1OUT&P2OUT and sum of arr2 on P3OUT&P4OUT  
* Modified by: A. Milenkovic, milenkovic@computer.org  
* Date         : September 14, 2008  
* Description: MSP430 IAR EW; Demonstration of the MSP430 assembler  
*-----*/  
  
#include "msp430.h"                ; #define controlled include file  
  
NAME      main                    ; module name  
  
PUBLIC    main                    ; make the main label visible  
                                ; outside this module  
  
ORG       0FFFFh  
DC16     init                      ; set reset vector to 'init' label  
  
RSEG     CSTACK                   ; pre-declaration of segment  
RSEG     CODE                     ; place program in 'CODE' segment  
  
init:    MOV      #SFE(CSTACK), SP ; set up stack
```

Sum up two integer arrays (ver1)

```
main:    NOP                                ; main program
        MOV.W    #WDTPW+WDTHOLD,&WDTCTL    ; Stop watchdog timer
        BIS.B    #0xFF,&P1DIR              ; configure P1.x as output
        BIS.B    #0xFF,&P2DIR              ; configure P2.x as output
        BIS.B    #0xFF,&P3DIR              ; configure P3.x as output
        BIS.B    #0xFF,&P4DIR              ; configure P4.x as output

        MOV      #arr1, R4                ; load the starting address of the array1 into the register R4
; Sum arr1 and display
        CLR      R7                        ; Holds the sum
        MOV      #8, R10                   ; number of elements in arr1
lnext1:  ADD      @R4+, R7                  ; get next element
        DEC      R10
        JNZ      lnext1
        MOV.B    R7, P1OUT                  ; display sum of arr1
        SWPB     R7
        MOV.B    R7, P2OUT

; Sum arr2 and display
        MOV      #arr2, R4
        CLR      R7                        ; Holds the sum
        MOV      #7, R10                   ; number of elements in arr2
lnext2:  ADD      @R4+, R7                  ; get next element
        DEC      R10
        JNZ      lnext2
        MOV.B    R7, P3OUT                  ; display sum of arr1
        SWPB     R7
        MOV.B    R7, P4OUT

        JMP      $

arr1     DC16    1, 2, 3, 4, 1, 2, 3, 4    ; the first array
arr2     DC16    1, 1, 1, 1, -1, -1, -1    ; the second array

        END
```




Subroutines

- A particular sub-task is performed many times on different data values
- Frequently used subtasks are known as subroutines
- Subroutines: How do they work?
 - Only one copy of the instructions that constitute the subroutine is placed in memory
 - Any program that requires the use of the subroutine simply branches to its starting location in memory
 - Upon completion of the task in the subroutine, the execution continues at the next instruction in the calling program



Subroutines (cont'd)

- CALL instructions:
perform the branch to subroutines
- RETURN instruction: the last instruction in the subroutine



Subroutine Nesting



Mechanisms for Passing Parameters

- Through registers
- Through stack
 - By value
 - Actual parameter is transferred
 - If the parameter is modified by the subroutine, the “new value” does not affect the “old value”
 - By reference
 - The address of the parameter is passed
 - There is only one copy of parameter
 - If parameter is modified, it is modified globally



Subroutine: SUMA_RP

- Subroutine for summing up elements of an integer array
- Passing parameters through registers
 - R12 - starting address of the array
 - R13 - array length
 - R14 - display id
(0 for P2&P1, 1 for P4&P3)

Subroutine: SUMA_RP

```
/*-----  
* Program : Subroutine for that sums up elements of an integer array  
* Input   : The input parameters are passed through registers:  
            R12 - starting address of the array  
            R13 - array length  
            R14 - display id (0 for P2&P1, 1 for P4&P3)  
* Output  : No output parameters  
*-----*/  
#include "msp430.h"                ; #define controlled include file  
  
PUBLIC suma_rp  
  
RSEG CODE  
  
suma_rp:  
    ; save the registers on the stack  
    PUSH    R7                    ; temporal sum  
    CLR     R7  
lnext:  ADD     @R12+, R7  
        DEC     R13  
        JNZ    lnext  
        BIT     #1, R14           ; display on P1&P2  
        JNZ    lp34             ; it's P3&P4  
        MOV.B  R7, P1OUT  
        SWPB  R7  
        MOV.B  R7, P2OUT  
        JMP    lend  
lp34:   MOV.B  R7, P3OUT  
        SWPB  R7  
        MOV.B  R7, P4OUT  
lend:   POP     R7                ; restore R7  
        RET  
        END
```



Sum Up Two Integer Arrays (ver2)

```
/*-----  
* Program      : Find a sum of two integer arrays using a subroutine (suma_rp.s43)  
* Input        : The input arrays are signed 16-bit integers in arr1 and arr2  
* Output       : Display sum of arr1 on P1OUT&P2OUT and sum of arr2 on P3OUT&P4OUT  
* Modified by: A. Milenkovic, milenkovic@computer.org  
* Date         : September 14, 2008  
* Description: MSP430 IAR EW; Demonstration of the MSP430 assembler  
*-----*/  
  
#include "msp430.h"                ; #define controlled include file  
  
NAME      main                    ; module name  
  
PUBLIC    main                    ; make the main label visible  
                                ; outside this module  
  
EXTERN    suma_rp  
  
ORG       0FFFFh  
DC16     init                    ; set reset vector to 'init' label  
  
RSEG     CSTACK                   ; pre-declaration of segment  
RSEG     CODE                     ; place program in 'CODE' segment  
  
init:    MOV     #SFE(CSTACK), SP  ; set up stack
```

Sum Up Two Integer Arrays (ver2)

```
main:  NOP                ; main program
      MOV.W   #WDTPW+WDTHOLD,&WDTCTL ; Stop watchdog timer
      BIS.B   #0xFF,&P1DIR          ; configure P1.x as output
      BIS.B   #0xFF,&P2DIR          ; configure P2.x as output
      BIS.B   #0xFF,&P3DIR          ; configure P3.x as output
      BIS.B   #0xFF,&P4DIR          ; configure P4.x as output

      MOV     #arr1, R12           ; put address into R12
      MOV     #8, R13              ; put array length into R13
      MOV     #0, R14              ; display #0 (P1&P2)
      CALL    #suma_rp

      MOV     #arr2, R12           ; put address into R12
      MOV     #7, R13              ; put array length into R13
      MOV     #1, R14              ; display #0 (P3&P4)
      CALL    #suma_rp
      JMP     $

arr1   DC16    1, 2, 3, 4, 1, 2, 3, 4 ; the first array
arr2   DC16    1, 1, 1, 1, -1, -1, -1 ; the second array

      END
```




Subroutine: SUMA_SP

- Subroutine for summing up elements of an integer array
- Passing parameters through the stack
 - The calling program prepares input parameters on the stack

Subroutine: SUMA_SP

```
-----  
/*  
 * Program : Subroutine for that sums up elements of an integer array  
 * Input  : The input parameters are passed through the stack:  
            starting address of the array  
            array length  
            display id  
 * Output : No output parameters  
-----*/  
#include "msp430.h"                ; #define controlled include file  
  
PUBLIC suma_sp  
  
RSEG CODE  
  
suma_sp:  
    ; save the registers on the stack  
    PUSH R7                        ; temporal sum  
    PUSH R6                        ; array length  
    PUSH R4                        ; pointer to array  
    CLR R7  
    MOV 10(SP), R6                 ; retrieve array length  
    MOV 12(SP), R4  
lnext: ADD @R4+, R7  
    DEC R6  
    JNZ lnext  
    MOV 8(SP), R4                 ; get id from the stack  
    BIT #1, R4                    ; display on P1&P2  
    JNZ lp34                      ; it's P3&P4  
    MOV.B R7, P1OUT  
    SWPB R7  
    MOV.B R7, P2OUT  
    JMP lend  
lp34:  MOV.B R7, P3OUT  
    SWPB R7  
    MOV.B R7, P4OUT  
lend:  POP R4                      ; restore R4  
    POP R6  
    POP R7  
    RET  
    END
```



Sum Up Two Integer Arrays (ver3)

```
*-----*
* Program      : Find a sum of two integer arrays
* Input        : The input arrays are signed 16-bit integers in arr1 and arr2
* Output       : Display sum of arr1 on P1OUT&P2OUT and sum of arr2 on P3OUT&P4OUT
* Modified by: A. Milenkovic, milenkovic@computer.org
* Date         : September 14, 2008
* Description: MSP430 IAR EW; Demonstration of the MSP430 assembler
*-----*/

#include "msp430.h"                ; #define controlled include file

NAME    main                       ; module name

PUBLIC  main                       ; make the main label visible
                           ; outside this module

EXTERN  suma_sp

ORG     0FFFEh
DC16    init                       ; set reset vector to 'init' label

RSEG    CSTACK                     ; pre-declaration of segment
RSEG    CODE                       ; place program in 'CODE' segment

init:   MOV     #SFE(CSTACK), SP    ; set up stack
```

Sum Up Two Integer Arrays (ver3)

```
main:  NOP                ; main program
      MOV.W   #WDTPW+WDTHOLD,&WDTCTL ; Stop watchdog timer
      BIS.B   #0xFF,&P1DIR           ; configure P1.x as output
      BIS.B   #0xFF,&P2DIR           ; configure P2.x as output
      BIS.B   #0xFF,&P3DIR           ; configure P3.x as output
      BIS.B   #0xFF,&P4DIR           ; configure P4.x as output

      PUSH   #arr1                ; push the address of arr1
      PUSH   #8                    ; push the number of elements
      PUSH   #0                    ; push display id
      CALL   #suma_sp              ; call suma_sp
      ADD    #6,SP                 ; collapse the stack

      PUSH   #arr2                ; push the address of arr1
      PUSH   #7                    ; push the number of elements
      PUSH   #1                    ; push display id
      CALL   #suma_sp              ; call suma_sp
      ADD    #6,SP                 ; collapse the stack

      JMP    $

arr1   DC16    1, 2, 3, 4, 1, 2, 3, 4 ; the first array
arr2   DC16    1, 1, 1, 1, -1, -1, -1 ; the second array

      END
```



The Stack and Local Variables

- Subroutines often need local workspace
- We can use a fixed block of memory space – *static allocation* – but:
 - The code will not be relocatable
 - The code will not be reentrant
 - The code will not be able to be called recursively
- Better solution: *dynamic allocation*
 - Allocate all local variables on the stack
 - **STACK FRAME** = a block of memory allocated by a subroutine to be used for local variables
 - **FRAME POINTER** = an address register used to point to the stack frame

Subroutine: SUMA_SPSF

```
/*-----  
* Program : Subroutine for that sums up elements of an interger array  
*           Subroutine variables are all allocated on the stack frame  
*           counter (SFP+2)  
*           sum (SFP+4)  
* Input   : The input parameters are passed through the stack:  
*           starting address of the array  
*           array length  
*           display id  
* Output  : No output parameters  
*-----*/  
#include "msp430.h"                ; #define controlled include file  
  
PUBLIC suma_sp  
  
RSEG CODE  
  
suma_sp:  
    ; save the registers on the stack  
    PUSH    R12                    ; save R12 - R12 is stack frame pointer  
    MOV     SP, R12                 ; R12 points on the bottom of the stack frame  
    SUB     #4, SP                  ; allocate 4 bytes for local varaibles  
    PUSH    R4                      ; pointer register  
    CLR     -4(R12)                 ; clear sum, sum=0  
    MOV     6(R12), -2(R12)         ; init count  
    MOV     8(R12), R4              ; R4 points to the array starting address  
  
lnext: ADD     @R4+, -4(R12)         ; add next element  
    DEC     -2(R12)                 ; decrement counter  
    JNZ     lnext  
    BIT     #1, 4(R12)              ; get id from the stack  
    JNZ     lp34                    ; it's P3&P4  
    MOV.B   -4(R12), P1OUT  
    MOV.B   -3(R12), P2OUT  
    JMP     lend  
lp34:  MOV.B   -4(R12), P3OUT  
    MOV.B   -3(R12), P4OUT  
lend:  POP     R4                    ; restore R4  
    ADD     #4, SP                  ; colapse the stack frame  
    POP     R12                     ; restore stack frame pointer  
    RET  
END
```



Sum Up Two Integer Arrays (ver4)

```
/*-----  
* Program      : Find a sum of two integer arrays  
* Input        : The input arrays are signed 16-bit integers in arr1 and arr2  
* Output       : Display sum of arr1 on P1OUT&P2OUT and sum of arr2 on P3OUT&P4OUT  
* Modified by: A. Milenkovic, milenkovic@computer.org  
* Date         : September 14, 2008  
* Description: MSP430 IAR EW; Demonstration of the MSP430 assembler  
*-----*/  
  
#include "msp430.h"                ; #define controlled include file  
  
NAME      main                    ; module name  
  
PUBLIC   main                    ; make the main label visible  
                           ; outside this module  
  
EXTERN   suma_sp  
  
ORG      0FFFEh  
DC16     init                    ; set reset vector to 'init' label  
  
RSEG     CSTACK                  ; pre-declaration of segment  
RSEG     CODE                    ; place program in 'CODE' segment  
  
init:    MOV      #SFE(CSTACK), SP ; set up stack
```

Sum Up Two Integer Arrays (ver3)

```
main:  NOP                ; main program
      MOV.W   #WDTPW+WDTHOLD,&WDTCTL ; Stop watchdog timer
      BIS.B   #0xFF,&P1DIR           ; configure P1.x as output
      BIS.B   #0xFF,&P2DIR           ; configure P2.x as output
      BIS.B   #0xFF,&P3DIR           ; configure P3.x as output
      BIS.B   #0xFF,&P4DIR           ; configure P4.x as output

      PUSH   #arr1                ; push the address of arr1
      PUSH   #8                    ; push the number of elements
      PUSH   #0                    ; push display id
      CALL   #suma_sp              ;
      ADD    #6,SP                 ; collapse the stack

      PUSH   #arr2                ; push the address of arr1
      PUSH   #7                    ; push the number of elements
      PUSH   #1                    ; push display id
      CALL   #suma_sp              ;
      ADD    #6,SP                 ; collapse the stack

      JMP    $

arr1   DC16    1, 2, 3, 4, 1, 2, 3, 4 ; the first array
arr2   DC16    1, 1, 1, 1, -1, -1, -1 ; the second array

      END
```




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- Assembly Language Programming
 - Adding two 32-bit numbers (decimal, integers)
 - Counting characters 'E'
- Subroutines
 - CALL&RETURN
 - Subroutine Nesting
 - Passing parameters
 - Stack and Local Variables
- C and the MSP430



Assembly Language and C

- We are interested in:
 - How a high-level language uses low-level language features?
 - C: System programming, device drivers, ...
 - Use of addressing modes by compilers
 - Parameter passing in assembly language
 - Local storage



C and the MSP430

- Compiler and the MSP430 instruction set
- C data types and implementation
- Storage classes
- Functions and parameters
- Pointers



Compiling a C Program: Example #1

```
#include "io430.h"
int main( void ) {
    int i1, i2;
    unsigned int uil;
    short int sint1;
    long int lint2;
    int a[4];
    // Stop watchdog timer to prevent time out reset
    WDTCTL = WDTPW + WDTNHOLD;
    i1 = 2; i2 = -2;
    uil=65535;
    sint1=127;
    lint2=128243;
    a[0]=20; a[1]=9;
    return 0;
}
```

Example #1 Compiler Generated List File (no optimization)

```
#####  
#  
# IAR MSP430 C/C++ Compiler V4.11C/W32 [Kickstart] 21/Sep/2008 20:24:33 #  
# Copyright 1996-2008 IAR Systems. All rights reserved. #  
# #  
# __rt_version = 3 #  
# __double_size = 32 #  
# __reg_r4 = free #  
# __reg_r5 = free #  
# __pic = no #  
# __core = 430 #  
# Source file = C:\Documents and Settings\Aleksandar\My #  
# Documents\Work\teaching\cpe323-08F\tutorial\test_dtypes #  
# .c #  
# Command line = "C:\Documents and Settings\Aleksandar\My #  
# Documents\Work\teaching\cpe323-08F\tutorial\test_dtypes #  
# .c" -lC "C:\Documents and Settings\Aleksandar\My #  
# Documents\Work\teaching\cpe323-08F\tutorial\Debug\List\ #  
# " -o "C:\Documents and Settings\Aleksandar\My #  
# Documents\Work\teaching\cpe323-08F\tutorial\Debug\Obj\" #  
# --no_cse --no_unroll --no_inline --no_code_motion #  
# --no_tbaa --debug -D__MSP430F149__ -e --double=32 -I #  
# "C:\Program Files\IAR Systems\Embedded Workbench #  
# 5.0\430\INC\" -Ol --multiplier=16 #  
# List file = C:\Documents and Settings\Aleksandar\My #  
# Documents\Work\teaching\cpe323-08F\tutorial\Debug\List\ #  
# test_dtypes.lst #  
# Object file = C:\Documents and Settings\Aleksandar\My #  
# Documents\Work\teaching\cpe323-08F\tutorial\Debug\Obj\t #  
# est_dtypes.r43 #  
# #  
# #
```

Example #1 Compiler Generated List File (no optimization)

```
1          #include "io430.h"
\
\          union <unnamed> volatile __data16 __A_WDTCTL
\          _A_WDTCTL:
\          000000          DS8 2
\
\          In segment CODE, align 2
2          int main( void ) {
\          main:
\          000000 0A12          PUSH.W R10
\          000002 0812          PUSH.W R8
\          000004 0912          PUSH.W R9
\          000006 3182          SUB.W #0x8, SP
3          int i1, i2;
          ^
Warning[Pe550]: variable "i1" was set but never used

          int i1, i2;
          ^
"C:\Documents and Settings\Aleksandar\My Documents\Work\teaching\cpe323-
08F\tutorial\test_dtypes.c",3 Warning[Pe550]:
          variable "i2" was set but never used
4          unsigned int ui1;
          ^
Warning[Pe550]: variable "ui1" was set but never used
5          short int sint1;
          ^
Warning[Pe550]: variable "sint1" was set but never used
6          long int lint2;
          ^
Warning[Pe550]: variable "lint2" was set but never used
7          int a[4];
          ^
Warning[Pe550]: variable "a" was set but never used
```

Example #1 Compiler Generated List File (no optimization)

```

8          // Stop watchdog timer to prevent time out reset
9          WDTCTL = WDTPW + WDT HOLD;
\ 000008   B240805A2001 MOV.W   #0x5a80, &0x120
10         i1 = 2; i2 = -2;
\ 00000E   2F43          MOV.W   #0x2, R15
\ 000010   3E40FEFF       MOV.W   #0xfffe, R14
11         uil=65535;
\ 000014   3D43          MOV.W   #0xffff, R13
12         sint1=127;
\ 000016   3A407F00       MOV.W   #0x7f, R10
13         lint2=128243;
\ 00001A   3840F3F4       MOV.W   #0xf4f3, R8
\ 00001E   1943          MOV.W   #0x1, R9
14         a[0]=20; a[1]=9;
\ 000020   B14014000000   MOV.W   #0x14, 0(SP)
\ 000026   B14009000200   MOV.W   #0x9, 0x2(SP)
15         return 0;
\ 00002C   0C43          MOV.W   #0x0, R12
\ 00002E   3152          ADD.W   #0x8, SP
\ 000030   3941          POP.W   R9
\ 000032   3841          POP.W   R8
\ 000034   3A41          POP.W   R10
\ 000036   3041          RET
\ 000038           REQUIRE  _A_WDTCTL
16         }

```

Maximum stack usage in bytes:

Function CSTACK

```

-----
main          16

```

Segment part sizes:

Function/Label Bytes

```

-----
_A_WDTCTL     2
main          56

```

56 bytes in segment CODE
2 bytes in segment DATA16_AN

56 bytes of CODE memory
0 bytes of DATA memory (+ 2 bytes shared)

Errors: none

Warnings: 6



C Data Types

Data type	Size	Range	Alignment
bool	8 bits	0 to 1	1
char	8 bits	to 255	1
signed char	8 bits	-128 to 127	1
unsigned char	8 bits	0 to 255	1
signed short	16 bits	-32768 to 32767	2
unsigned short	16 bits	0 to 65535	2
signed int	16 bits	-32768 to 32767	2
unsigned int	16 bits	0 to 65535	2
signed long	32 bits	-2^{31} to $2^{31}-1$	2
unsigned long	32 bits	0 to $2^{32}-1$	2
signed long long	64 bits	-2^{63} to $2^{63}-1$	2
unsigned long long	64 bits	0 to $2^{64}-1$	2
float	32 bits		2
double	32 bits		2 (*)
double	64 bits		



C Data Types, cont'd

- Local variables
 - Defined inside a function
 - Cannot be accessed from outside the function
 - Normally lost when a return from the function is made
- Global variables
 - Defined outside a function
 - Can be accessed both from inside and outside the function
- Variables defined in a block exist only within that block

```
int i; /*global variable, visible to everything from this point*/
void function_1(void) /*A function with no parameters*/
{
    int k; /*Integer k is local to function_1*/
    {
        int q; /*Integer q exists only in this block*/
        int j; /*Integer j is local and not the same as j in main*/
    }
}
void main(void)
{
    int j; /*Integer j is local to this block within function main*/
} /*This is the point at which integer j ceases to exist*/
```



Storage Class Specifiers

- **auto**
 - Variable is no longer required once a block has been left;
Default
- **register**
 - Ask compiler to allocate the variable to a register
 - Also is automatic
 - Cannot be accessed by means of pointers
- **static**
 - Allows local variable to retain its value when a block is reentered
 - Initialized only once, by the compiler!
- **extern**
 - Indicates that the variable is defined outside the block
 - The same global variable can be defined in more than one module



Storage Class Modifiers

- **volatile**
 - To define variables that can be changed externally
 - Compiler will not put them in registers
 - Think about Status Registers !
- **const**
 - Variable may not be changed during the execution of a program
 - Cannot be changed unintentionally, but CAN be changed externally (as a result of an I/O, or OS operations external to the C program)
- Type conversion
 - In C, done either automatically or explicitly (casting)



Compiling a C Program: Example #2

```
#include "io430.h"
int main( void ) {
    volatile int i1, i2;
    volatile unsigned int uil;
    volatile short int sint1;
    volatile long int lint2;
    volatile int a[4];
    // Stop watchdog timer to prevent time out reset
    WDTCTL = WDTPW + WDTXLD;
    i1 = 2; i2 = -2;
    uil=65535;
    sint1=127;
    lint2=128243;
    a[0]=20; a[1]=9;
    return 0;
}
```

Example #2 Compiler Generated List File (no optimization)

```
C:\Documents and Settings\Aleksandar\My Documents\Work\teaching\cpe323-
08F\tutorial\test_dtypes.c
 1          #include "io430.h"

\
\          In segment DATA16_AN, at 0x120
\  union <unnamed> volatile __data16 _A_WDTCTL
\          __A_WDTCTL:
\ 000000          DS8 2

\          In segment CODE, align 2
 2          int main( void ) {
\          main:
\ 000000 31801400      SUB.W   #0x14, SP
 3          volatile int i1, i2;
 4          volatile unsigned int ui1;
 5          volatile short int sint1;
 6          volatile long int lint2;
 7          volatile int a[4];
 8          // Stop watchdog timer to prevent time out reset
 9          WDTCTL = WDTPW + WDTHOLD;
\ 000004 B240805A2001 MOV.W   #0x5a80, &0x120
10          i1 = 2; i2 = -2;
\ 00000A A1430000      MOV.W   #0x2, 0(SP)
\ 00000E B140FEFF0200 MOV.W   #0xffff, 0x2(SP)
11          ui1=65535;
\ 000014 B1430400      MOV.W   #0xffff, 0x4(SP)
12          sint1=127;
\ 000018 B1407F000600 MOV.W   #0x7f, 0x6(SP)
13          lint2=128243;
\ 00001E B140F3F40800 MOV.W   #0xf4f3, 0x8(SP)
\ 000024 91430A00      MOV.W   #0x1, 0xa(SP)
```

Example #2 Compiler Generated List File (no optimization)

```
14          a[0]=20; a[1]=9;
\   000028  B14014000C00 MOV.W   #0x14, 0xc(SP)
\   00002E  B14009000E00 MOV.W   #0x9, 0xe(SP)
15          return 0;
\   000034  0C43             MOV.W   #0x0, R12
\   000036  31501400         ADD.W   #0x14, SP
\   00003A  3041             RET
\   00003C                REQUIRE  _A_WDTCTL
16          }
```

Maximum stack usage in bytes:

```
Function CSTACK
-----
main      22
```

Segment part sizes:

```
Function/Label Bytes
-----
_A_WDTCTL      2
main           60
```

60 bytes in segment CODE
2 bytes in segment DATA16_AN

60 bytes of CODE memory
0 bytes of DATA memory (+ 2 bytes shared)

Errors: none
Warnings: none



Factorial

```
#include "stdio.h"
#include "io430.h"

int fact(int n);

int main(void) {
    int n = 5;
    int nf;
    nf = fact(n);
    printf("n=%d, nf=%d\n", n, nf);
    return 0;
}

int fact(int n) {
    if(n>1) return n*fact(n-1);
    else return 1;
}
```

Factorial: List File

```
1      # include "stdio.h"
2      #include "io430.h"
4      int fact(int n);
\
\          In segment CODE, align 2
6      int main(void) {
\          main:
\ 000000 0A12      PUSH.W  R10
\ 000002 0B12      PUSH.W  R11
7
8      int n = 5;
\ 000004 3A400500  MOV.W   #0x5, R10
9
10     int nf;
11
12     nf = fact(n);
\ 000008 0C4A      MOV.W   R10, R12
\ 00000A B012....  CALL   #fact
\ 00000E 0B4C      MOV.W   R12, R11
13
14     printf("n=%d, nf=%d\n", n, nf);
\ 000010 0B12      PUSH.W  R11
\ 000012 0A12      PUSH.W  R10
\ 000014 3C40....  MOV.W   #`?<Constant "n=%d, nf=%d\n">`, R12
\ 000018 B012....  CALL   #printf
15
16     return 0;
\ 00001C 0C43      MOV.W   #0x0, R12
\ 00001E 2152      ADD.W   #0x4, SP
\ 000020 3B41      POP.W   R11
\ 000022 3A41      POP.W   R10
\ 000024 3041      RET
17     }
```


Factorial: List File

```
19      int fact(int n) {
\
\      fact:
\      000000 0A12      PUSH.W  R10
\      000002 0A4C      MOV.W   R12, R10
20
21      if(n>1) return n*fact(n-1);
\      000004 2A93      CMP.W   #0x2, R10
\      000006 0E38      JL     ??fact_0
\      000008 0C4A      MOV.W   R10, R12
\      00000A 3C53      ADD.W   #0xffff, R12
\      00000C B012....  CALL   #fact
\      000010 0212      PUSH.W  SR
\      000012 32C2      DINT
\      000014 824A3001 MOV.W   R10, &0x130
\      000018 824C3801 MOV.W   R12, &0x138
\      00001C 1C423A01 MOV.W   &0x13a, R12
\      000020 3241      POP.W   SR
\      000022 013C      JMP    ??fact_1
22      else return 1;
\      ??fact_0:
\      000024 1C43      MOV.W   #0x1, R12
\      ??fact_1:
\      000026 3A41      POP.W   R10
\      000028 3041      RET
23      }

\
\      In segment DATA16_C, align 1, align-
sorted
\      `?<Constant "n=%d, nf=%d\\n">`:
\      000000 6E3D25642C20 DC8 "n=%d, nf=%d\012"
\      6E663D25640A
\      00
```



Functions and Parameters

```
#include "io430.h"
void swapbyv(int a, int b);
void swapbyr(int *a, int *b);
int main( void )
{
    // Stop watchdog timer to prevent time out reset
    WDCTL = WDTPW + WDTMOD;
    int x = 5;
    int y = 6;
    // pass parameters by value
    swapbyv(x, y);
    // pass parameters by reference
    swapbyr(&x, &y);

    return 0;
}
```

```
void swapbyv(int a, int b) {
    int temp;
    temp = a;
    a = b;
    b = temp;
}

void swapbyr(int *a, int *b) {
    int temp;
    temp = *a;
    *a = *b;
    *b = temp;
}
```

Functions and Parameters

```
8      int main( void )
\          main:
9      {
\ 000000 2182          SUB.W   #0x4, SP
10         // Stop watchdog timer to prevent time out reset
11         WDTCTL = WDTPW + WDTHOLD;
\ 000002 B240805A2001 MOV.W   #0x5a80, &0x120
12
13         int x = 5;
\ 000008 B14005000200 MOV.W   #0x5, 0x2(SP)
14         int y = 6;
\ 00000E B14006000000 MOV.W   #0x6, 0(SP)

19         swapbyv(x, y);
\ 000014 2D41          MOV.W   @SP, R13
\ 000016 1C410200    MOV.W   0x2(SP), R12
\ 00001A B012....     CALL   #swapbyv

24         swapbyr(&x, &y);
\ 00001E 0D41          MOV.W   SP, R13
\ 000020 0C41          MOV.W   SP, R12
\ 000022 2C53          ADD.W   #0x2, R12
\ 000024 B012....     CALL   #swapbyr

29         return 0;
\ 000028 0C43          MOV.W   #0x0, R12
\ 00002A 2152          ADD.W   #0x4, SP
\ 00002C 3041          RET
\ 00002E 00002E     REQUIRE _A_WDTCTL

30     }
```

Functions and Parameters

```

\
\          In segment CODE,
align 2
32      void swapbyv(int a, int b) {
\          swapbyv:
33      int temp;
34
35      temp = a;
\ 000000 0F4C      MOV.W   R12, R15
36      a = b;
\ 000002 0C4D      MOV.W   R13, R12
37      b = temp;
\ 000004 0D4F      MOV.W   R15, R13
38      }
\ 000006 3041      RET
39

\          In segment CODE,
align 2
40      void swapbyr(int *a, int *b) {
\          swapbyr:
41      int temp;
42
43      temp = *a;
\ 000000 2F4C      MOV.W   @R12, R15
44      *a = *b;
\ 000002 AC4D0000  MOV.W   @R13, 0(R12)
45      *b = temp;
\ 000006 8D4F0000  MOV.W   R15, 0(R13)
46      }
\ 00000A 3041      RET

```

Maximum stack usage in bytes:

Function	CSTACK
-----	-----
main	6
-> swapbyv	6
-> swapbyr	6
swapbyr	2
swapbyv	2

Segment part sizes:

Function/Label	Bytes
-----	-----
_A_WDTCTL	2
main	46
swapbyv	8
swapbyr	12

66 bytes in segment CODE
2 bytes in segment DATA16_AN

66 bytes of CODE memory
0 bytes of DATA memory (+ 2 bytes shared)



Pointers and C

```
#include "io430.h"
#include "stdio.h"

int main( void ) {
    // Stop watchdog timer to prevent time out reset
    WDTCTL = WDTPW + WDTCTL;
    int x = 5; // an integer x
    int *p_x; // a pointer to int
    int y1; // an integer y1 (uninitialized)
    long int y2, y3; // long integers y2, y3
    long int *p_y2; // a pointer to long integer
    char mya[20] = "hello world, cpe323!"; // character array
    char *p_my_a; // pointer to character

    p_x = &x; // p_x points to x
    y1 = 10 + x; // new value to y1
    y2 = -1;
    p_y2 = &y2; // pointer p_y2 points to y2
    y3 = 10 + *p_y2;
    p_my_a = mya; // p_my_a points to array mya
    p_my_a = p_my_a + 3;

    // display addresses and variables in terminal i/o
    printf("a.x=%x, x=%x\n", &x, x);
    printf("a.p_x=%x, p_x=%x\n", &p_x, p_x);
    printf("a.y1=%x, y1=%x\n", &y1, y1);
    printf("a.y2=%x, y2=%lx\n", &y2, y2);
    printf("a.y3=%x, y3=%lx\n", &y3, y3);
    printf("a.p_y2=%x, p_y2=%x\n", &p_y2, p_y2);
    printf("a.mya=%x, mya=%s\n", &mya, mya);
    printf("a.p_my_a=%x, p_my_a=%x\n", &p_my_a, p_my_a);
    return 0;
}
```

Pointers and C, cont'd

```
1      #include "io430.h"

\
\          In segment DATA16_AN, at 0x120
\  union <unnamed> volatile __data16 _A_WDTCTL
\          _A_WDTCTL:
\ 000000          DS8 2
2      #include "stdio.h"
3

\
\          In segment CODE, align 2
4      int main(void) {
\          main:
\ 000000 31802600  SUB.W  #0x26, SP
5          // Stop watchdog timer to prevent time out reset
6          WDTCTL = WDTPW + WDTHOLD;
\ 000004 B240805A2001 MOV.W  #0x5a80, &0x120
7          int x = 5; // an integer x
\ 00000A B14005000000 MOV.W  #0x5, 0(SP)
8          int *p_x; // a pointer to int
9          int y1; // an integer y1 (uninitialized)
10         long int y2, y3; // long integers y2, y3
11         long int *p_y2; // a pointer to long integer
12         char mya[20] = "hello world, cpe323!"; // character array
\ 000010 0C41          MOV.W  SP, R12
\ 000012 3C501200  ADD.W  #0x12, R12
\ 000016 3E40....  MOV.W  #'?<Constant "hello world, cpe323!">', R14
\ 00001A 3D401400  MOV.W  #0x14, R13
\ 00001E B012....  CALL  #?CopyMemoryBytes
13         char *p_mya; // pointer to character
14
15         p_x = &x; // p_x points to x
\ 000022 0F41          MOV.W  SP, R15
\ 000024 814F0800  MOV.W  R15, 0x8(SP)
```

Pointers and C, cont'd

```
16          y1 = 10 + x;      // new value to y1
\ 000028  2F41          MOV.W  @SP, R15
\ 00002A  3F500A00     ADD.W  #0xa, R15
\ 00002E  814F0600     MOV.W  R15, 0x6(SP)
17          y2 = -1;
\ 000032  B1430A00     MOV.W  #0xffff, 0xa(SP)
\ 000036  B1430C00     MOV.W  #0xffff, 0xc(SP)
18          p_y2 = &y2;      // pointer p_y2 points to y2
\ 00003A  0F41          MOV.W  SP, R15
\ 00003C  3F500A00     ADD.W  #0xa, R15
\ 000040  814F0400     MOV.W  R15, 0x4(SP)
19          y3 = 10 + *p_y2;
\ 000044  1F410400     MOV.W  0x4(SP), R15
\ 000048  2E4F          MOV.W  @R15, R14
\ 00004A  1F4F0200     MOV.W  0x2(R15), R15
\ 00004E  3E500A00     ADD.W  #0xa, R14
\ 000052  0F63          ADDC.W #0x0, R15
\ 000054  814E0E00     MOV.W  R14, 0xe(SP)
\ 000058  814F1000     MOV.W  R15, 0x10(SP)
20          p_my_a = my_a;   // p_my_a points to array my_a
\ 00005C  0F41          MOV.W  SP, R15
\ 00005E  3F501200     ADD.W  #0x12, R15
\ 000062  814F0200     MOV.W  R15, 0x2(SP)
21          p_my_a = p_my_a + 3;
\ 000066  B15003000200 ADD.W  #0x3, 0x2(SP)
```



Speed and Performance of Microprocessors

- Why is difficult to compare the speed of two microprocessors?
 - Performance
 - Execution time
 - MIPS: Million of Instructions Per Second
- Carefully interpret benchmarks!
- Clock Cycles/Bus Cycles

Speed and Performance of Microprocessors, cont'd

```
#include "msp430.h"                ; #define controlled include file
    NAME    main                    ; module name
    PUBLIC  main                    ; make the main label visible
                                        ; outside this module

    ORG     0FFFFh
    DC16    init                    ; set reset vector to 'init' label
    RSEG    CSTACK                  ; pre-declaration of segment
    RSEG    CODE                    ; place program in 'CODE' segment
init:    MOV     #SFE(CSTACK), SP    ; set up stack
main:    NOP                        ; main program
    MOV.W   #WDTPW+WDTHOLD,&WDTCTL ; Stop watchdog timer
    PUSH   R14                      ;
    MOV    SP, R14                  ; R14 points to the top of the stack
    MOV    #aend, R6
    MOV    R6, R5
    SUB    #arr1, R5                ; how many bytes is in the array
    SUB    R5, SP                  ; allocate storage for array on the stack
lnext:   DEC    R6                  ; decrement pointer to arr1
    DEC    R14                     ; decrement pointer on the stack
    MOV.B  @R6, 0(R14)
    DEC    R5
    JNZ    lnext
    JMP    $
    NOP

arr1     DC8    1, 2, 3, 4, 5, 6, 7, 8, 9
aend

    END
```

Speed and Performance of Microprocessors, cont'd

```

#include "msp430.h"                ; #define controlled include file
    NAME    main                  ; module name
    PUBLIC  main                  ; make the main label visible
                                      ; outside this module

    ORG     0FFFFh
    DC16    init                  ; set reset vector to 'init' label
    RSEG    CSTACK                ; pre-declaration of segment
    RSEG    CODE                  ; place program in 'CODE' segment
init:  MOV    #SFE(CSTACK), SP    ; 4 cc
main:  NOP                          ; 1 cc
      MOV.W  #WDTPW+WDTHOLD,&WDTCTL ; 5 cc
      PUSH  R14                    ; 3 cc (table 3.15)
      MOV   SP, R14                ; 1 cc
      MOV   #aend, R6              ; 2 cc
      MOV   R6, R5                 ; 1 cc
      SUB   #arr1, R5              ; 2 cc
      SUB   R5, SP                 ; 1 cc
lnext: DEC   R6                    ; 1 cc x 9
      DEC   R14                   ; 1 cc x 9
      MOV.B @R6, 0(R14)           ; 4 cc x 9
      DEC   R5                    ; 1 cc x 9
      JNZ   lnext                 ; 2 cc x 9
      JMP  $

arr1   DC8    1, 2, 3, 4, 5, 6, 7, 8, 9
aend

      END

TOTAL NUMBER OF CLOCK CYLES:      4+1+5+3+1+2+1+2+1+9x(1+1+4+1+2) = 20+9x9 = 101 cc
TOTAL NUMBER OF INSTRUCTIONS      9+9x5 = 54 instructions
CPI                                101/54 = 1.87 cc/instruction

```